

LOCAL GALILEI TRANSFORMATIONS

[E15] *Local Galilei transformations of dual frame and local connection forms*

Let $(e_A) = (v, e_a)$ be a local Galilei frame on a Galilei manifold (M, τ, h) . A local Galilei transformation by a (locally defined) Gal-valued function (R, k) is the change of local Galilei frame according to

$$(v, e_a) \rightarrow (\tilde{v}, \tilde{e}_a) = (v, e_a) \cdot (R, k)^{-1} = \left(v - e_b (R^{-1})^b_a k^a, e_b (R^{-1})^b_a \right). \quad (1)$$

- (a) Determine how the dual frame $(e^A) = (\tau, e^a)$ and the local connection form (ω^a_b, ϖ^a) of a Galilei connection change under the above change of frame for a *purely rotational* local Galilei transformation, i.e. with $k = 0$.

Hint: Write the frame change in matrix form. Then use that for a basis change $\tilde{e}_A = A^B_A e_B$, the dual basis changes as $\tilde{e}^A = (A^{-1})^A_B e^B$; and that for a connection on a principal bundle whose structure group is a matrix Lie group, local connection forms in general transform under change of local section according to

$$(\sigma \cdot g^{-1})^* \omega = g \cdot (\sigma^* \omega) \cdot g^{-1} + g \cdot d(g^{-1}). \quad (2)$$

You should obtain the transformation formulae from proposition 3.16 (i).

- (b) Determine how $(e^A) = (\tau, e^a)$ and (ω^a_b, ϖ^a) transform under a Milne boost, i.e. a local Galilei boost, i.e. a local Galilei transformation with $R = \mathbb{1}$.

Hint: Proceed as for the rotations. You should obtain the formulae from proposition 3.16 (ii).

[E16] *Deriving Milne boosts of the covariant space metric and the Newton–Coriolis form*

Using the transformation behaviour of (e^A) and ϖ^a , compute how the covariant space metric $h_{\tilde{v}} = \delta_{ab} e^a \otimes e^b$ and the Newton–Coriolis form $\Omega = \delta_{ab} \varpi^a \wedge e^b$ with respect to v transform under the Milne boost $v \rightarrow \tilde{v} = v - k^a e_a$ parametrised by (k^a) . Show that you obtain the behaviour as stated in proposition 1.19.

Hint: To compare to proposition 1.19, note that for the vector field $k = k^a e_a$, the corresponding one-form is $k^b = h_{\tilde{v}}(k, \cdot) = \delta_{ab} k^a e^b$. Compute dk^b from this expression, and re-express de^a in terms of the torsion via proposition 3.14 (ii).